

Package ‘leidenbase’

May 8, 2026

Type Package

Title R and C/C++ Wrappers to Run the Leiden find_partition() Function

Version 0.1.36

Description An R to C/C++ interface that runs the Leiden community detection algorithm to find a basic partition (). It runs the equivalent of the 'leidenalg' find_partition() function, which is given in the 'leidenalg' distribution file 'leiden/src/functions.py'. This package includes the required source code files from the official 'leidenalg' distribution and functions from the R 'igraph' package. The 'leidenalg' distribution is available from <https://github.com/vtraag/leidenalg/> and the R 'igraph' package is available from <https://igraph.org/r/>. The Leiden algorithm is described in the article by Traag et al. (2019) <[doi:10.1038/s41598-019-41695-z](https://doi.org/10.1038/s41598-019-41695-z)>. Leidenbase includes code from the packages:
igraph version 0.9.8 with license GPL (>= 2),
leidenalg version 0.8.10 with license GPL 3.

Imports igraph (>= 0.9.0)

License GPL-3

Encoding UTF-8

RoxygenNote 7.3.1

Depends R (>= 3.5.0)

Suggests rmarkdown, knitr, testthat (>= 3.1.0), pandoc

URL <https://github.com/cole-trapnell-lab/leidenbase>

BugReports <https://github.com/cole-trapnell-lab/leidenbase/issues>

NeedsCompilation yes

Maintainer Brent Ewing <bge@uw.edu>

VignetteBuilder knitr

Author Brent Ewing [aut, cre],
 Vincent Traag [ctb],
 Gábor Csárdi [ctb],
 Tamás Nepusz [ctb],
 Szabolcs Horvat [ctb],
 Fabio Zanini [ctb]

Repository CRAN

Date/Publication 2025-12-16 03:30:02 UTC

Contents

| | |
|---------------------------------|----------|
| leiden_find_partition | 2 |
| Index | 5 |

leiden_find_partition *Leiden find partition community detection function*

Description

R to C wrapper that runs the basic Leiden community detection algorithm, which is similar to the `find_partition()` function in the python Leidenalg distribution.

Usage

```
leiden_find_partition(
  igragh,
  partition_type = c("CPMVertexPartition", "ModularityVertexPartition",
    "RBConfigurationVertexPartition", "RBERVertexPartition",
    "SignificanceVertexPartition", "SurpriseVertexPartition"),
  initial_membership = NULL,
  edge_weights = NULL,
  node_sizes = NULL,
  seed = NULL,
  resolution_parameter = 0.1,
  num_iter = 2,
  verbose = FALSE
)
```

Arguments

`igragh` R igraph graph.

`partition_type` String partition type name. Default is CPMVertexParition.

`initial_membership` Numeric vector of initial membership assignments of nodes. These are 1-based indices. Default is one community per node.

| | |
|----------------------|--|
| edge_weights | Numeric vector of edge weights. Default is 1.0 for all edges. |
| node_sizes | Numeric vector of node sizes. Default is 1 for all nodes. |
| seed | Numeric random number generator seed. The seed value must be either NULL for random seed values or greater than 0 for a fixed seed value. Default is NULL. |
| resolution_parameter | Numeric resolution parameter. The value must be greater than 0.0. Default is 0.1. The resolution_parameter is ignored for the partition_types ModularityVertexPartition, SignificanceVertexPartition, and SurpriseVertexPartition. |
| num_iter | Numeric number of iterations. Default is 2. |
| verbose | A logic flag to determine whether or not we should print run diagnostics. |

Details

The Leiden algorithm is described in From Louvain to Leiden: guaranteeing well-connected communities. V. A. Traag and L. Waltman and N. J. van Eck Scientific Reports, 9(1) (2019) DOI: 10.1038/s41598-019-41695-z.

Significance is described in Significant Scales in Community Structure V. A. Traag, G. Krings, and P. Van Dooren Scientific Reports, 3(1) (2013) DOI: 10.1038/srep02930

Notes excerpted from `leidenalg/src/VertexPartition.py`

- *CPMVertexPartition* Implements Constant Potts Model. This quality function uses a linear resolution parameter and is well-defined for both positive and negative edge weights.
- *ModularityVertexPartition* Implements modularity. This quality function is well-defined only for positive edge weights.
- *RBConfigurationVertexPartition* Implements Reichardt and Bornholdt's Potts model with a configuration null model. This quality function uses a linear resolution parameter and is well-defined only for positive edge weights.
- *RBERVertexPartition* Implements Reichardt and Bornholdt's Potts model with an Erdos-Renyi null model. This quality function uses a linear resolution parameter and is well-defined only for positive edge weights.
- *SignificanceVertexPartition* Implements Significance. This quality function is well-defined only for unweighted graphs.
- *SurpriseVertexPartition* Implements (asymptotic) Surprise. This quality function is well-defined only for positive edge weights.

Value

A named list consisting of a numeric vector of the node community memberships (1-based indices), a numeric quality value, a numeric modularity, a numeric significance, a numeric vector of edge weights within each community, a numeric vector of edge weights from each community, a numeric vector of edge weights to each community, and total edge weight in the graph.

Index

leiden_find_partition, [2](#)